

Circular motion and Complex Exponential (Eugene Yablonski)

1. CIRCULAR MOTION WITH CONSTANT SPEED

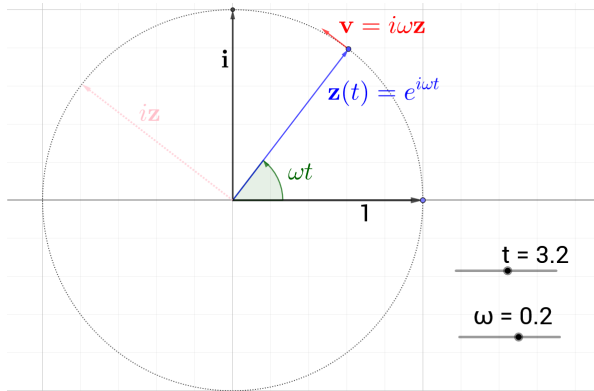
Exercise 1.1. Your boat makes a circle of radius $r = 1\text{km}$ at a constant angular speed $\omega = 1^\circ/\text{min} = \frac{\pi}{180}$ rad/min.

If your initial position \mathbf{x}_0 has polar coordinates $(1, \phi)$, what is your position at time t ?

SOLUTION. By time t , you've traveled ωt rad. Let $A(\omega t)$ be the matrix of rotation by angle ωt .

Then your new position is

$$\mathbf{x}(t) = A(\omega t)\mathbf{x}_0 = \begin{bmatrix} \cos(\omega t + \phi) \\ \sin(\omega t + \phi) \end{bmatrix}.$$



Exercise 1.2. Describe the same movement on a complex plane.

ANSWER:

$$\boxed{z(t) = e^{i\omega t} z_0} = e^{i(\omega t + \phi)}.$$

Remark. Your **velocity vector** is

$$z'(t) = \omega iz(t).$$

Multiplication by i rotates z by 90° , so that the *velocity vector* $z'(t)$ is perpendicular to the current radius-vector $z(t)$.

Your displacement over $\Delta t = 1$ min is

$$\Delta z \approx z'(t)\Delta t = \omega iz(t)1,$$

that is you move about $\omega = \frac{\pi}{180}$ km in the direction $iz(t)$ tangent to the circle.